

Inferring the Spatial Structure of the Pleiades

A Bayesian approach

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- Learn statistics
- Spatial structure *per se*
- Will be used to infer membership probabilities.

- 1 Analyse the data.
- 2 Select *a priori* the model(s) according to data.
- 3 Construct a probabilistic framework for the model.
- 4 Use Bayes theorem and MCMC to:
 - Check accuracy and precision with mock data.
 - Obtain the posterior for the parameters.
- 5 Analyse the posteriors.

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Methodology

Mock Data

Real Data

Model
Selection

Discussion

KPNO/Mosaic1
 UKIRT/WFCAM
 Subaru/SuprimeCam
 CFHT/CFHT12K
INT/WFC
CFHT/UH8K
KPNO/NEWFIRM
GTO/MOSAIC2
CFHT/MegaCam

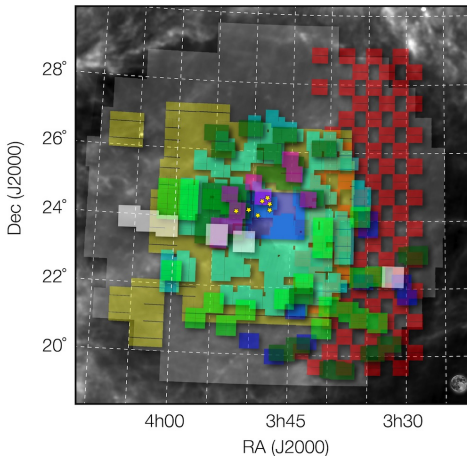


Table: Number of stars at different R_{max}

1°	2°	3°	4°	5°	6°
496	1028	1354	1576	1735	1805

Table 4: True positive rates and contamination rates for different values of the membership threshold. The uncertainty intervals correspond to the range of values (maximum-minimum) observed in the five random samples.

p_{min}	0.50	0.7	0.8	0.90	0.95	0.96	0.97	0.98	0.99	0.9975
TPR (%)	98.4±0.5	97.1±0.7	96.0±0.9	92.9±1.5	88.0±2.8	85.9±3.0	82.6±3.2	76.7±4.9	63.8±7.7	36.3±7.7
CR (%)	11.0±2.0	8.0±1.5	6.6±1.3	4.5±1.1	2.9±0.5	2.6±0.6	2.1±0.5	1.6±0.3	1.1±0.3	0.4±0.4

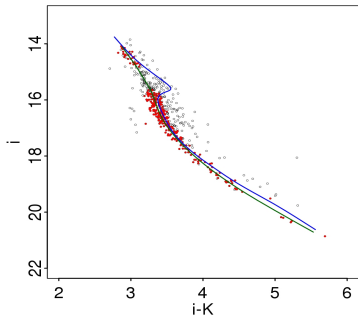


Fig. 2: Principal curve fits to the initial reference set (blue line) and to the subset of sources with all magnitudes fainter than its closest point in the first principal curve (green line). This subset of points is represented in red.

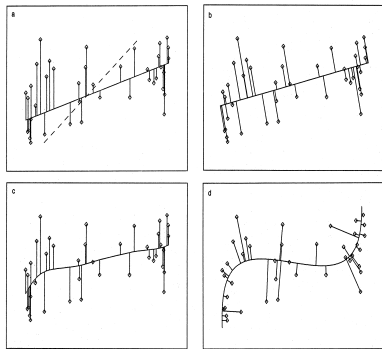


Figure 1. (a) The linear regression line minimizes the sum of squared deviations in the response variable. (b) The principal-component line minimizes the sum of squared deviations in all of the variables. (c) The smooth regression curve minimizes the sum of squared deviations in the response variable, subject to smoothness constraints. (d) The principal curve minimizes the sum of squared deviations in all of the variables, subject to smoothness constraints.

Hastie & Stuetzle, 1989

Bayes theorem.

$$p(\theta | D, I) = \frac{p(D | \theta, I)p(\theta | I)}{p(D | I)}$$

Evidence,

$$p(D | I) = Z = \int P(D | \theta, I)P(\theta | I)d\theta$$

The generative model, $p(D | \theta, I)$, is a pdf.

$$\int p(D | \theta, I)dD = 1. \quad (1)$$

"I will say that you have a *generative model* of data point n if you can write down or calculate a pdf $p(D_n | \theta, I)$ for the measurement D_n , conditional on a vector or list θ of parameters and a (possibly large) number of other things I (*prior information*) on which the D_n pdf depends, such as assumptions, or approximations, or knowledge about the noise process, or so on." Hogg 2012.

We used the classical surface density families of models:

$$King = S_c \left(\frac{1}{\sqrt{1 + \frac{r^2}{r_c^2}}} - \frac{1}{\sqrt{1 + \frac{r_t^2}{r_c^2}}} \right)^2$$

$$Plummer = S_c \left(1 + \frac{r^2}{r_c^2} \right)^{-2},$$

modified by:

- Field density S_f as a Contamination ratio

$$Cr = \frac{\pi R_{max}^2 S_f}{N}.$$

- r_c as a linear function of Sarro's et al. (2014) λ ,

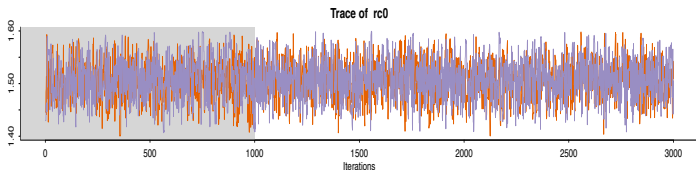
$$r_c = r_{c0} + r_{c1}\lambda.$$

$$\begin{aligned}
 p(r | r_c) &= \frac{dN(r)}{N_{tot}} \frac{1}{dr} \\
 &= \frac{2\pi S_0 r \left(1 + \frac{r^2}{r_c^2}\right)^{-2}}{\pi S_0 r_c^2} \frac{1}{dr} \\
 &= 2 \frac{r}{r_c^2} \left(1 + \frac{r^2}{r_c^2}\right)^{-2}.
 \end{aligned}$$

If data are truncated, as in our case, the pdf in the interval $(0, R_{max})$ is

$$p(r | r_c) = 2 \frac{r}{R_{max}^2} \frac{\left(1 + \frac{R_{max}^2}{r_c^2}\right)}{\left(1 + \frac{r^2}{r_c^2}\right)^2}.$$

- MCMC Sampler: Stan (mc-stan.org, Hoffman-Gelman, 2011).
- Convergence, R-hat criterion (Gelman & Rubin, 1992).



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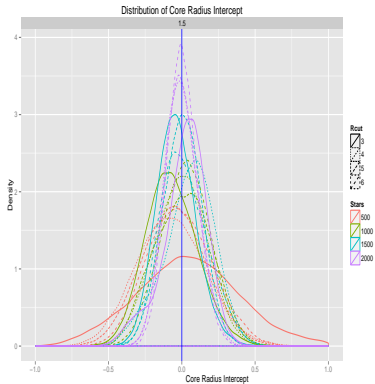
Methodology

Mock Data

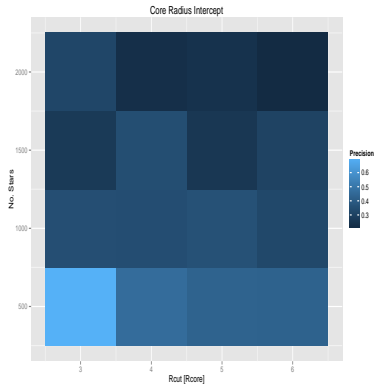
Real Data

Model Selection

Discussion



Accuracy



Precision

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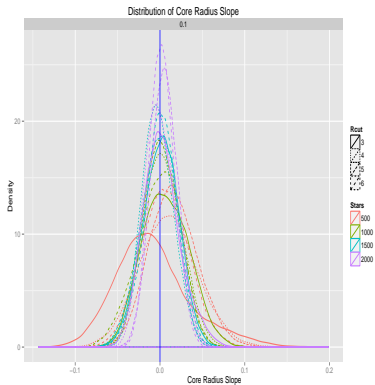
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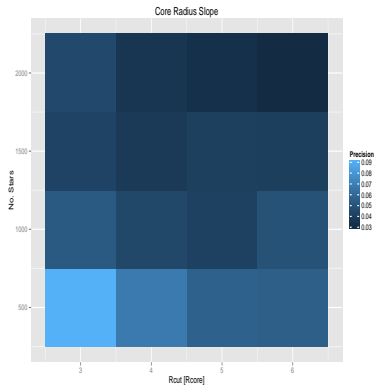
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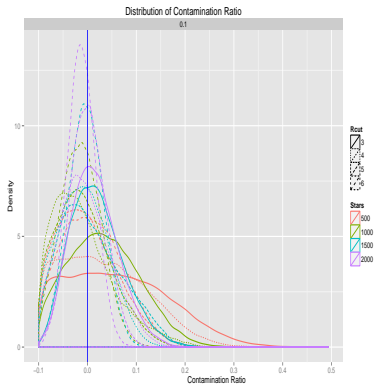
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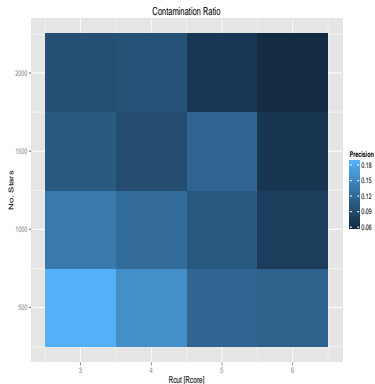
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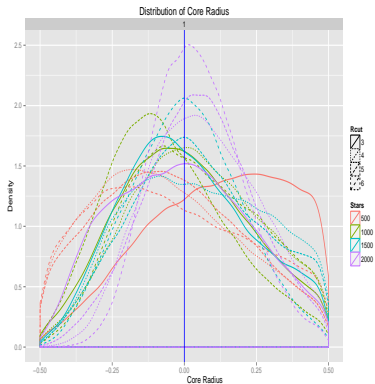
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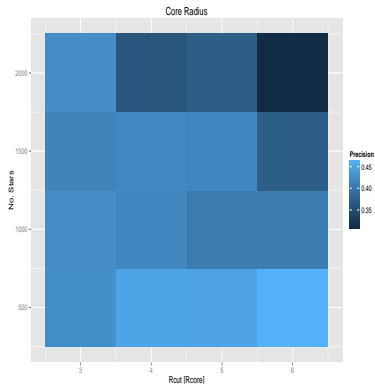
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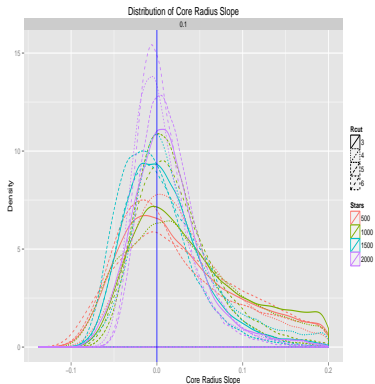
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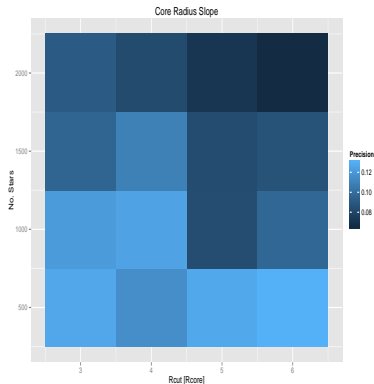
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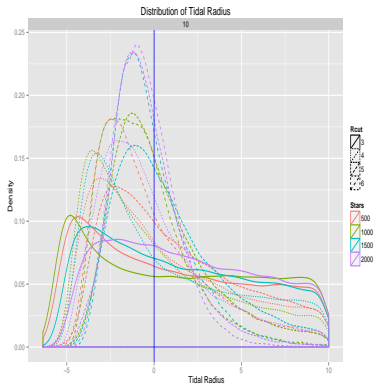
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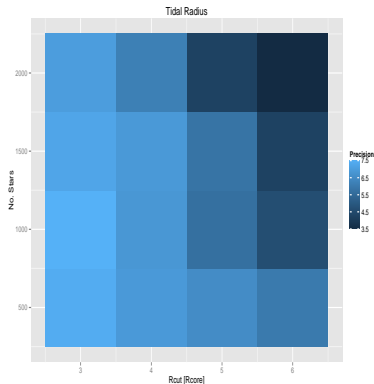
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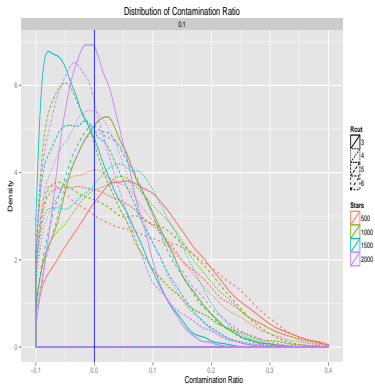
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Mock Data

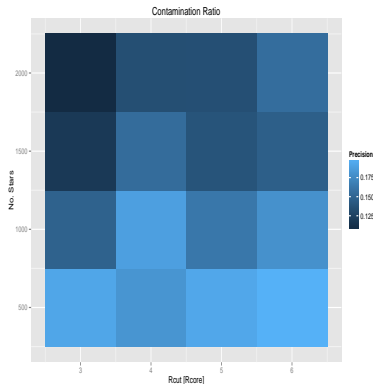
Real Data

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Accuracy



Precision

Real Data: Plummer v1 Contamination

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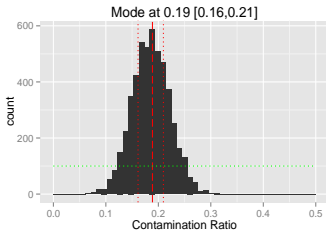
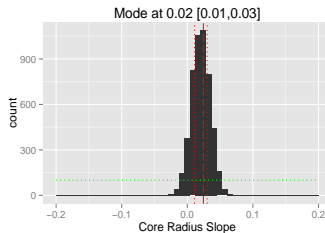
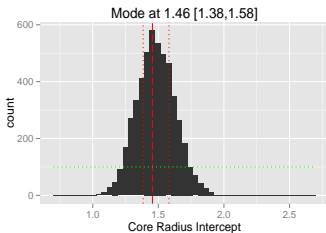
Mock Data

Real Data

Model
Selection

Discussion

Posterior distributions and their MAP



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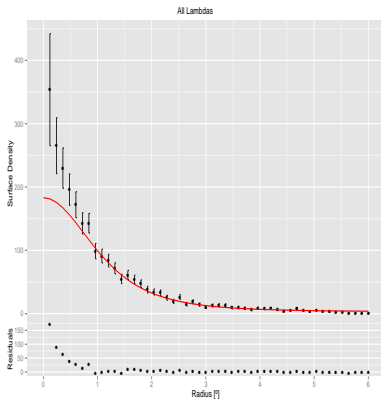
Methodology

Mock Data

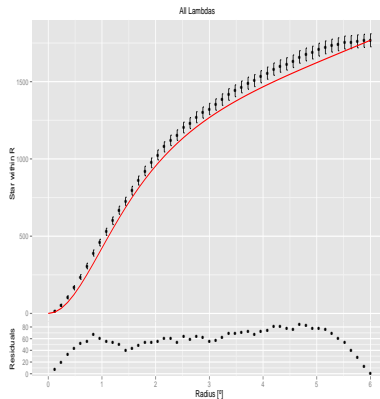
Real Data

Model Selection

Discussion



Number Density



Number

Inferring the Spatial Structure of the Pleiades

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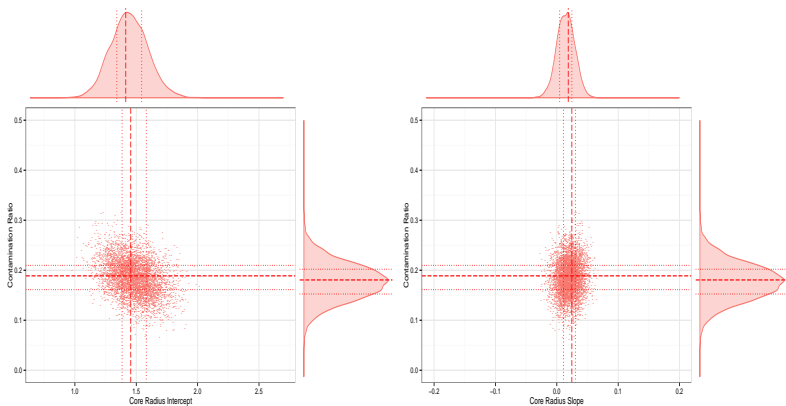
Methodology

Mock Data

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Real Data: King v1 Contamination

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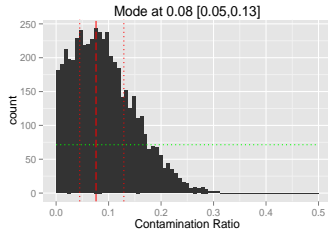
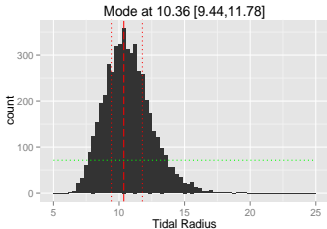
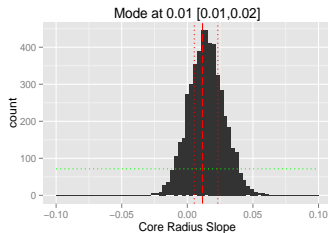
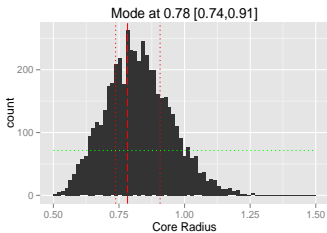
Mock Data

Real Data

Model
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Unnormalized Posteriors and their MAPs



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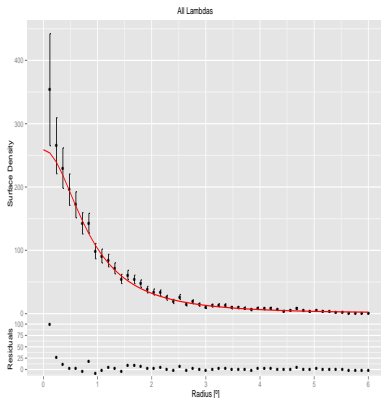
Methodology

Mock Data

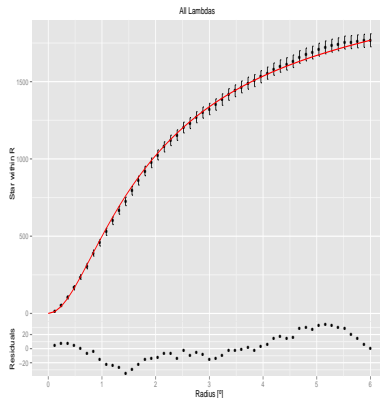
Real Data

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Number Density



Number

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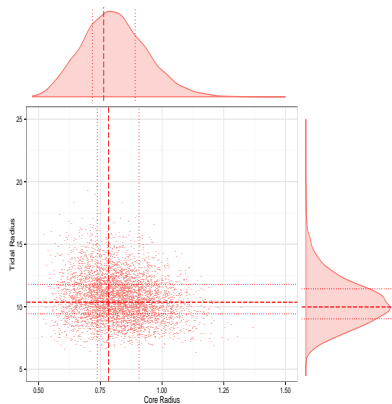
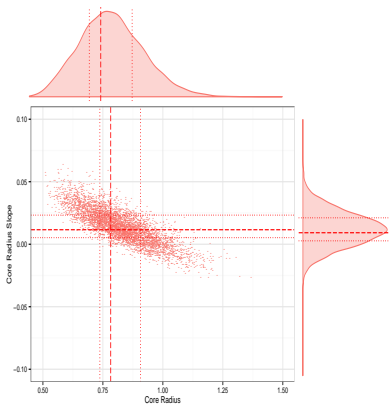
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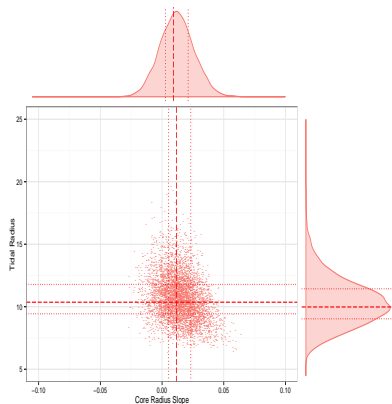
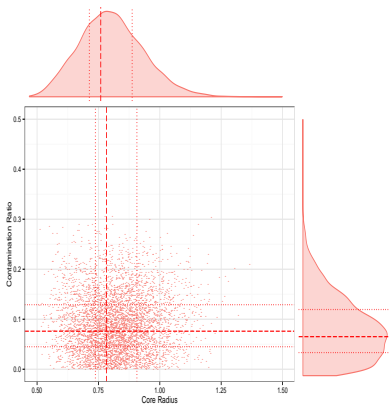
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Real Data: King v1 Contamination

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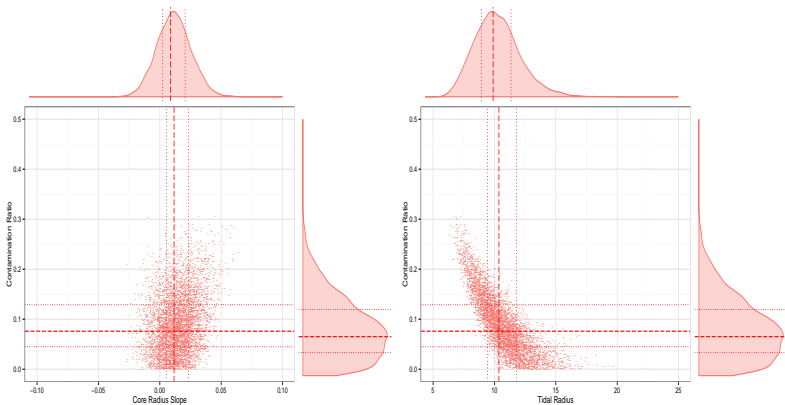
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Use evidence to select appropriate model,

$$K_{12} = \frac{P(D | M_1)}{P(D | M_2)} = \frac{\int P(D | \theta_1, I)P(\theta_1 | I)d\theta_1}{\int P(D | \theta_2, I)P(\theta_2 | I)d\theta_2} = \frac{Z_1}{Z_2}$$

Approximate Z by HMA (Newton and Raftery, 1994),

$$Z_{HMA} = \left(\frac{1}{m} \sum_i^m p(D | \theta^i) \right)^{-1}.$$

Table: $\text{Log}Z_{HMA}$. Plummer Models with varying R_{max}

Model	3°	4°	5°	6°
v_0	0.56	-1.29	-1.77	-1.95
v_0 Cr	-0.91	-1.44	-1.35	-0.57
v_1	0.30	0.57	-0.21	0.28
v_1 Cr	0.87	0.54	0.38	0.28

Table: $\text{Log}Z_{HMA}$. King Models with varying R_{max}

Model	3°	4°	5°	6°
v_0	-0.18	-1.86	-1.43	-2.03
v_0 Cr	0.82	-1.55	-1.52	-1.11
v_1	-0.91	-1.44	-1.35	-0.57
v_1 Cr	0.87	0.57	0.38	0.23

Using the distance to the Pleiades (136.2 pc, Melis et al. 2014)

Table: King v1 cr [68 % interval]

Parameter	6°
r_{c0} [pc]	1.84 [1.75-2.15]
r_{c1} [pc/ λ]	0.02 [0.0-0.05]
r_t [pc]	24.6 [22.4-27.9]
cr	0.08 [0.05,0.13]

Table 3. Pleiades King fit results.

Bin (M_{\odot})	r_c (pc)	r_c limits (68 per cent confidence)	k	k limits (68 per cent confidence)	n	Mass
1	0.91	[0.50-1.51]	1.86	[0.87-3.74]	13	66
2	1.38	[1.15-1.66]	10.04	[7.86-12.69]	115	190
3	2.22	[1.98-2.49]	15.90	[14.17-17.81]	300	249
4	2.91	[2.63-3.23]	32.81	[30.51-35.37]	766	230

$r_t = 13.1$ pc, Cluster depth = ± 0.2 mag
 $M_c = 735 M_{\odot}$, $N_c = 1194$, $\bar{m}_c = 0.616 M_{\odot}$

Figure: Pinfield's values

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- Estimate de Credibility intervals.
- Determina the false positive rate of lambda segregation.
- Infer the number of stars.
- Try different Profiles (e.g. Elson, Fall & Freeman,1987)